

MATH 2040 A Lecture 2 (Sep 12, 2016)

Revision II (Textbook Ch. 1-4)

Recall: $\beta \subseteq V$ basis

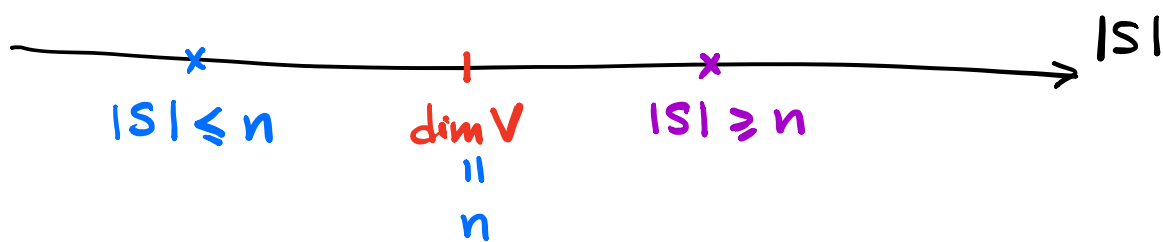
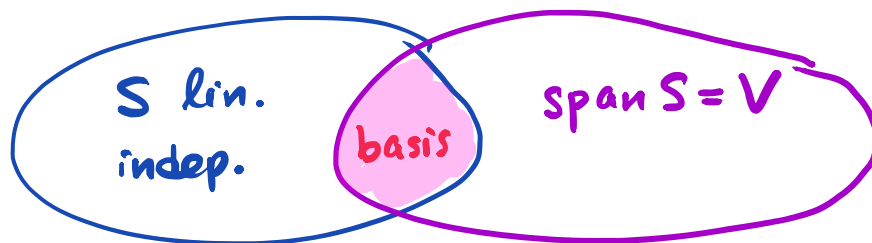
$$\dim V = |\beta|$$

$$\Leftrightarrow \textcircled{1} \text{ span}(\beta) = V$$

$$\textcircled{2} \beta \text{ lin. indep.}$$

of vectors
in β

$S \subseteq V$ subset of vectors



Thm: V vector space / \mathbb{F} ($= \mathbb{R}$ or \mathbb{C})

$$\dim V = n < +\infty.$$

$$(a) S \subseteq V \text{ lin. indep.} \Rightarrow |S| \leq n$$

$$(b) \text{span } S = V \Rightarrow |S| \geq n$$

Thm: (a) Any lin. indep $S \subseteq V$ can be extended to a basis of V .

$$S = \{\vec{v}_1, \dots, \vec{v}_k\} \xrightarrow{\text{lin. indep.}} \beta = \{\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$$

$(k \leq n)$
basis

(b) $W \subseteq V$ subspace $\Rightarrow \dim W \leq \dim V$

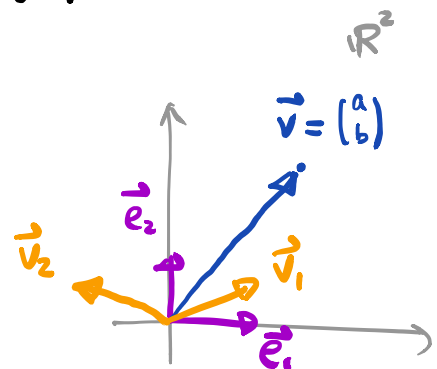
"=" holds $\Leftrightarrow W = V$.

Example: $\vec{v} = \begin{pmatrix} a \\ b \end{pmatrix} = a \cdot \vec{e}_1 + b \cdot \vec{e}_2$

$$\vec{v} \stackrel{\cong}{\longleftrightarrow} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\vec{v} = c \vec{v}_1 + d \vec{v}_2$$

$$\vec{v} \stackrel{\cong}{\longleftrightarrow} \begin{pmatrix} c \\ d \end{pmatrix}$$



Remark: $\beta = \{\vec{v}_1, \dots, \vec{v}_n\}$ basis for V ($\dim V = n$)

For each $\vec{v} \in V$, \exists unique $a_1, \dots, a_n \in \mathbb{F}$ s.t.

$$\vec{v} = a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_n \vec{v}_n$$

$$\begin{array}{ccc} V & \xrightarrow{\cong} & \mathbb{F}^n \\ \downarrow \cong & & \downarrow \cong \\ \vec{v} & \xrightarrow{\beta} & \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \end{array}$$

§ System of Linear Equations

m equations, n unknowns (x_1, \dots, x_n)

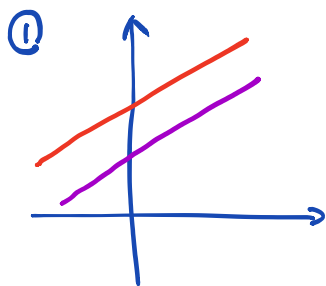
$$(*) \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

3 possibilities

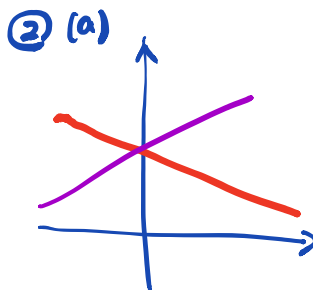
- ① NO SOLUTION
- ② \exists SOLUTION
 - (a) ONLY 1 SOLUTION "best"
 - (b) \exists ∞ 'ly many solutions

Geometrically, $(*) \Leftrightarrow$ intersection of lines/planes
(hyperplanes in \mathbb{R}^n)

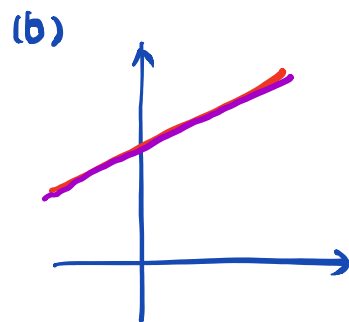
$n=m=2$:



NO SOLUTION



UNIQUE SOLⁿ
"generic"



∞ 'LY MANY
SOLⁿ

Written in terms of matrix/vectors

$$(*) \Leftrightarrow \underbrace{\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}}_A \underbrace{\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}}_{\substack{\mathbb{R}^n \\ n \times 1}} = \underbrace{\begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}}_{\substack{\mathbb{R}^m \\ m \times 1}}$$

$\underbrace{\hspace{10em}}_{\substack{\text{m} \times \text{n} \text{ matrix} \\ \text{rows} \quad \text{col}^{\text{s}}}}$

$$(*) \Leftrightarrow \boxed{A \vec{x} = \vec{b}}$$

Idea: " A^{-1} exists" $\Rightarrow \vec{x} = A^{-1} \vec{b}$.

$(M_{m \times n}(\mathbb{F}), +, \cdot)$ is a vector space \mathbb{F} .
(dim = mn)

Matrix multiplication:

$$\begin{matrix} A & B & = & C \\ \text{m} \times \text{n} & \text{n} \times \text{k} & & \text{m} \times \text{k} \end{matrix}$$

• $A(B+C) = AB + AC$ etc.

Caution: $AB \neq BA$ (non-commutativity)

but $(AB)C = A(BC)$ O.K.

Defⁿ: $A \in M_{n \times n}(\mathbb{F})$ is invertible

if $\exists A^{-1} \in M_{n \times n}(\mathbb{F})$ s.t.

"the" inverse
of A

$$A^{-1}A = I (= AA^{-1})$$

"

$$\begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

"identity
matrix"

$$IA = A \\ \forall A.$$

Question: When is A invertible?

(quick) Ans: use "determinants".

Thm: $A \in M_{n \times n}(\mathbb{F})$ \iff "det $A \neq 0$."
invertible

§ Determinants

$A \in M_{n \times n}(\mathbb{F})$, define "recursively" (on n)

$$(\#) \quad \det A := \sum_{j=1}^n (-1)^{i+j} A_{ij} \det(\tilde{A}_{ij})$$

"expansion along i^{th} row"

Remark: freedom to pick i^{th} row.

n=1: $A = (a)$ $\det A = a$

$$\begin{cases} ax = b \\ \Rightarrow x = a^{-1}b \end{cases}$$
 $a \neq 0!$

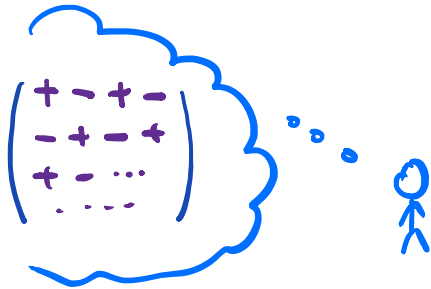
n=2: $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow \det A = ad - bc$
 \parallel

(#): $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a d - b c$

n=3: $\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = -a_{21} \cdot \det \begin{pmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{pmatrix}$

$+ a_{22} \cdot \det \begin{pmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{pmatrix}$

$- a_{23} \cdot \det \begin{pmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{pmatrix}$



Theorems: (A) $\star \boxed{\det(A B) = \det(A) \det(B)} \star$

Ex / Caution: $\det(A + B) \neq \det(A) + \det(B)$

$\det(c A) \neq c \det(A)$
 $\stackrel{\text{IF}}{\neq}$

BUT: $\det(c A) = c^n \det(A)$

$A \in M_{n \times n}(\text{IF})$

$$(B) \det(A^T) = \det(A)$$

↑
transpose of A

$$\text{Eg. } \det \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \det \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}.$$

(A) \Rightarrow Thm: $\det A \neq 0 \iff A$ invertible

"Quick Proof": A invertible

$$\text{By def: } \exists A^{-1} \text{ s.t. } A^{-1}A = I$$

$$\det(A^{-1}A) = \det I = 1$$

$$\begin{aligned} & \text{"} \\ & \det(A^{-1}) \det(A) \Rightarrow \det(A) \neq 0. \end{aligned}$$

□

Problem: If $A \in M_{n \times n}(\mathbb{F})$ s.t. $\det A \neq 0$,
then how to find A^{-1} ?

$$(A \mid I) \xrightarrow{\text{"row operations"}} (I \mid A^{-1})$$

RREF of $(A \mid I)$.

§ Row operations & RREF.

- Elementary row op. (I) $\textcircled{i} \leftrightarrow \textcircled{j}$
(col.)
- (II) $\alpha \textcircled{i}$, $\alpha \in \mathbb{F}$
- (III) $\alpha \textcircled{i} + \textcircled{j}$

- Elementary matrices: applying (I), (II), (III) to I.

F.g: $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \xleftarrow{r^{\textcircled{1}}+r^{\textcircled{2}}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I$

"Elem. row (col.) operations" \Leftrightarrow "Multiply by elem. matrices from the left (right)"

By elem. row op., any matrix has a unique RREF
(reduced row echelon form)

$$R = \begin{pmatrix} 1 & * & 0 & * & 0 & * & 0 & * \\ 0 & 0 & 1 & * & 0 & * & 0 & * \\ \vdots & \vdots & & & & & & \\ 0 & 0 & 0 & & 1 & * & 0 & * \\ & & & & & & 1 & * \\ & & & & & & & 0 \end{pmatrix} \quad \text{"pivots"}$$

$$\Rightarrow \text{rank}(A) = \# \text{ of "pivots"}$$

$$= \dim(C(A))$$

column

space of A

$$A = \begin{pmatrix} | & | & & | \\ \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \\ | & | & & | \end{pmatrix}$$

$$:= \text{span}(\vec{a}_1, \dots, \vec{a}_n)$$

FACTS: • Every invertible $A \in M_{n \times n}(\mathbb{F})$
can be written as

$$A = \underbrace{E_1 E_2 \cdots E_k}_{\substack{\text{product of} \\ \text{elementary} \\ \text{matrices}}}$$

• Let P, Q be invertible. Then

$$\text{rank}(PAQ) = \text{rank}(A)$$